

MATH 54 FINAL

#1 If $\{f_1, f_2, f_3\}$ is a linearly independent set of functions from \mathbb{R} to \mathbb{R} then the Wronskian $W(f_1, f_2, f_3)(t) \neq 0$ for all t .

A. TRUE

B. FALSE

#2 If $\{\vec{v}_1, \dots, \vec{v}_n\}$ is a set of nonzero orthogonal vectors then $\{\vec{v}_1, \dots, \vec{v}_n\}$ is linearly independent.

A. TRUE

B. FALSE

#3 Is the following set $\left\{ \begin{bmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix}, \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$ orthonormal?

A. TRUE

B. FALSE

#4 Two independent real solutions to $x'' + 2x' + 2x = 0$ are:

A. e^t, e^{2t}

B. $e^{(1+i)t}, e^{(1-i)t}$

C. $e^{-t}\sin t, e^{-t}\cos t$ D. $e^{t}\sin t, e^{t}\cos t$.

#5 The solution to the initial-value problem:

$$x'' + 2x' + 2x = 0, \quad x(0) = 0, \quad x'(0) = 1$$

A. Does not exist

B. $C_1 e^{-t}\sin t + C_2 e^{-t}\cos t$

C. $e^{-t}\sin t$.

#6 Let E denote the standard basis for \mathbb{R}^2 i.e. $E = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$ and

$\mathcal{B} = \left\{ \begin{bmatrix} -5 \\ 3 \end{bmatrix}, \begin{bmatrix} 3 \\ 2 \end{bmatrix} \right\}$. The change of basis matrix $\mathcal{B} \xrightarrow{\Phi} E$ is:

A. $\begin{bmatrix} 2 & -3 \\ -3 & 5 \end{bmatrix}$

B. $\begin{bmatrix} 5 & 3 \\ 3 & 2 \end{bmatrix}$

C. $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

D. None of these.

#7 The matrix $A = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$ is diagonalizable?

A. TRUE

B. FALSE

#8 The system of ODEs $\begin{cases} y'' - 2x' + y = 0 \\ x'' + y' + x - y = 0 \end{cases}$ can be turned into

the matrix equation $\vec{x}' = A\vec{x}$ where $\vec{x} = \begin{bmatrix} x \\ y \\ x' \\ y' \end{bmatrix}$, $A = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & 1 & 0 & 1 \\ 0 & -1 & 2 & 0 \end{bmatrix}$

A. TRUE

B. FALSE

#9 Given is the ODE $x'' + 2x' + 1 = te^{-t}$. The correct guess for x_p according to the method of undetermined coefficients is:

- A. $(At+B)e^{-t}$ B. Ct^2e^{-t} C. $t^2(At+B)e^{-t}$ D. $t(At+B)e^{-t}$.

#10 Let $\vec{x}_1, \vec{x}_2, \vec{x}_3$ be 3 linearly independent vectors in \mathbb{R}^n ($n \geq 3$) and let $\vec{v}_1, \vec{v}_2, \vec{v}_3$ be orthogonal vectors obtained from the Gram-Schmidt process on $\{\vec{x}_1, \vec{x}_2, \vec{x}_3\}$. Then:

$$\vec{v}_1 = \vec{x}_1, \quad \vec{v}_2 = \vec{x}_2 - \frac{\vec{x}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1, \quad \vec{v}_3 = \vec{x}_3 - \frac{\vec{x}_3 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \frac{\vec{x}_3 \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2$$

A. TRUE

B. FALSE

#11 Suppose A : a 3×3 matrix has a basis of orthonormal eigenvectors $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$. Let $Q = [\vec{v}_1 \ \vec{v}_2 \ \vec{v}_3]$. Which of the following matrix is always diagonal?

- A. $Q^T A Q$ B. $Q A Q^T$ C. $Q A Q^{-1}$ D. None of these

#12 The set $\left\{ \begin{bmatrix} a+2 \\ b-a \\ b-a+1 \end{bmatrix} \mid a, b \in \mathbb{R} \right\}$ is a subspace of \mathbb{R}^3 ?

A. TRUE

B. FALSE

#13 Let $A = \begin{bmatrix} 1 & 2 \\ 0 & 0 \\ 1 & 3 \end{bmatrix}$ and $\vec{b} = \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}$

13.1 One least-square solution $\hat{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ to the linear equation

$A\vec{x}' = \vec{b}'$ is obtained by solving $A\vec{x}' = \vec{c}'$ where \vec{c}' is:

A. $\begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}$

B. $\begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix}$

C. $\begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}$

D. $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$

13.2 The normal equation to $A\vec{x}' = \vec{b}'$ is:

$$2x_1 + 5x_2 = 2$$

$$5x_1 + 13x_2 = 9$$

A. TRUE

B. FALSE

#14 Let $A = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix}$. e^{At} is:

A. $\begin{bmatrix} e^{-t} & 0 \\ 0 & e^{2t} \end{bmatrix}$

B. $\begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix}$

C. Neither A nor B

#15 Given is the ODE $x'' + x = \tan t$, $t \in (-\pi/2, \pi/2)$. According to the method of variation of parameters, a particular solution

$$x_p(t) = v_1(t) \cos t + v_2(t) \sin t$$

where $\vec{v}_1(t), \vec{v}_2(t)$ are:

A. $\int -\tan t \sin t dt, \int \tan t dt$ B. $\int -\frac{\sin^2 t}{\cos t} dt, \int \cos t dt$ C. $\int \tan t dt, \int -\frac{\sin^2 t}{\cos t} dt$.

16 Let $A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{bmatrix}$ and $\beta = \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} \right\}$ is a basis for \mathbb{R}^3 .

16.1 The matrix $[A]$ is
 $B \leftarrow \beta$

A. $\begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{bmatrix}$

B. $\begin{bmatrix} 6 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

C. $\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$

16.2 The eigenvalues for A are:

A. $\lambda = 1, 2, 3$

B. $\lambda = 0, 6$

C. $\lambda = -1, 2$

17 Given is the ODE $x'' - 2x' + 2 = t \text{etant}$. According to the method of undetermined coefficients, a particular solution x_p has the form:

A. $A t \text{etant}$

B. $t(At+B) \text{etant} + t(Ct+D) e^{2t} \cos t$

C. $t(At+B) e^{2t} \sin t$

18 Let $\vec{u} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$, $\vec{v} = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$, then $\text{proj}_{\vec{u}} \vec{v} =$

A. $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

B. $\begin{bmatrix} 6/5 \\ 3/5 \\ 0 \end{bmatrix}$

C. $\begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$

D. None of these.

19 The general solution to $y''' - 2y'' - 5y' + 6y = 0$ is:

A. $C_1 e^x + C_2 e^{-2x} + C_3 e^{3x}$

B. $C_1 e^x + C_2 x e^x + C_3 x^2 e^x$

C. Neither

20 Let A be an orthogonal $m \times m$ matrix. Then $\text{Row } A = \text{Col } A$

A. TRUE

B. FALSE

#21 If $A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{bmatrix}$, $\vec{u} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$. So $A\vec{u} = 6\vec{u}$. Then $e^{At}\vec{u}$ is:

A. $\begin{bmatrix} e^{6t} \\ 2e^{6t} \\ 3e^{6t} \end{bmatrix}$

B. $\begin{bmatrix} e^{At} \\ 2e^{At} \\ 3e^{At} \end{bmatrix}$

C. $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$

D. None of these

#22 Let $A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 3 & 0 \\ 0 & 1 & 1 \end{bmatrix}$ and let $\vec{u} = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}$ be a generalized

eigenvector (but not an eigenvector) of A corresponding to $\lambda = 1$.

Then $e^{At}\vec{u} =$

A. $\begin{bmatrix} -2e^t \\ e^t \\ te^t \end{bmatrix}$

B. $\begin{bmatrix} -2e^t \\ e^t \\ 0 \end{bmatrix}$

C. $\begin{bmatrix} -2e^{At} \\ e^{At} \\ 0 \end{bmatrix}$

D. None of these.

#23 If \vec{v}_1, \vec{v}_2 are two linearly independent eigenvectors of A and $A\vec{v}_1 = \lambda_1\vec{v}_1$, $A\vec{v}_2 = \lambda_2\vec{v}_2$, then: $\lambda_1 \neq \lambda_2$:

A. TRUE

B. FALSE

#24 Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ be a one to one linear transformation.

Then $\dim(\text{range } T) =$

A. 2

B. 3

C. 1

D. 0

#25 Given that $y_1(t) = \frac{1}{4} \sin 2t$ is a solution to $y'' + 2y' + 4y = \cos 2t$

and that $y_2(t) = \frac{t}{4} - \frac{1}{8}$ is a solution to $y'' + 2y' + 4y = t$. Then a

solution to $y'' + 2y' + 4y = 2t - 3 \cos 2t$ is:

A. $-\frac{3}{4} \sin 2t + \frac{t}{2} - \frac{1}{4}$

B. $\frac{1}{4} \sin 2t + \frac{t}{4} - \frac{1}{8}$

C. $\sin 2t + t - 1$

#26 (12 pts) Given is the initial-value problem:

$$y'' - 3y' + 2y = te^{2t} \quad y(0)=1, \quad y'(0)=1$$

Solve the problem using both methods: undetermined coefficients and Variation of parameters.

27 (12 pts) Solve the following initial value problem:

$$\vec{x}'(t) = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \vec{x}(t) + \begin{bmatrix} e^{2t} \\ 0 \end{bmatrix} \quad \vec{x}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$$

28 (10 pts) Let $T: \mathbb{P}_2 \rightarrow \mathbb{P}_2$ be

$$T(a_0 + a_1t + a_2t^2) = (a_0 - a_2) + (a_1 - 2a_2)t + a_0t^2$$

and $\mathcal{B} = \{1, 1-t, t-t^2\}$ be a basis for $\text{dom}(T)$, $\mathcal{C} = \{1, 1+t, 1+t^2\}$ be

a basis for codomain(T). Compute $[T]_{\mathcal{B}}^{\mathcal{C}}$ and $[T(1+t+t^2)]_{\mathcal{C}}$.

29 (12 pts) Let $\vec{v} = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$ and $H : x+y+z=0$ - Compute
 $\text{proj}_H \vec{v}$ and $\text{dist}(\vec{v}, \text{proj}_H \vec{v})$.